

Unit V Maxwell Equations

$$(i) \quad \nabla \cdot \vec{E} = \rho / \epsilon_0 \quad \left(\text{Gauss law for electrostatics} \right)$$

$$(ii) \quad \nabla \cdot \vec{B} = 0 \quad \left(\text{Net magnetic flux for closed surface is always zero} \right)$$

$$(iii) \quad \nabla \times \vec{E} = - \frac{d\vec{B}}{dt} \quad \left(\text{Faraday's law for electromagnetic induction} \right)$$

$$(iv) \quad \nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{d\vec{E}}{dt}$$

(Ampere's law with Maxwell modification)

where $\rho \rightarrow$ volume charge density
 $\epsilon_0 \rightarrow$ permittivity of free space.
 $\vec{J} \rightarrow$ current density
 $\mu_0 \rightarrow$ permeability of free space

Displacement vector $\vec{D} = \epsilon_0 \vec{E}$

$$\vec{B} = \mu_0 \vec{H}$$

or
Magnetic field intensity $\vec{H} = \frac{\vec{B}}{\mu_0}$

Maxwell Equations in terms of Displacement Vector \vec{D} and \vec{H} .

$$(i) \quad \vec{\nabla} \cdot \vec{D} = \rho$$

$$(ii) \quad \vec{\nabla} \cdot \vec{H} = 0$$

$$(iii) \quad \vec{\nabla} \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t}$$

$$(iv) \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \frac{\partial \vec{D}}{\partial t}$$

$$(i) \quad \vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$$

Proof:- According to Gauss law of Electrostatics

$$\phi_E = \oint \vec{E} \cdot d\vec{s} = \frac{q}{\epsilon_0} \quad \text{--- (1)}$$

By using Gauss divergence theorem we can write

$$\oint_S \vec{E} \cdot d\vec{s} = \int_V (\vec{\nabla} \cdot \vec{E}) dV$$

therefore (1) \Rightarrow

$$\int_V (\vec{\nabla} \cdot \vec{E}) dV = \frac{q}{\epsilon_0} \quad \text{--- (2)}$$

Now from definition of volume charge density $\rho = \frac{dq}{dV}$ or $q = \int \rho dV$

So

② \Rightarrow

$$\int_V (\vec{\nabla} \cdot \vec{E}) dV = \frac{1}{\epsilon_0} \int \rho dV$$

By comparing both sides we ~~can~~ have

$$\boxed{\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$$

Derivations :-

Maxwell's Second Equation :-

We know that magnetic flux is defined as

$$\Phi_B = \oint_S \vec{B} \cdot d\vec{S} \quad \text{--- (1)}$$

for magnetic field, magnetic field lines always make closed loop. i.e. there is no source or sink. therefore net magnetic flux is always zero. So we can write

$$\text{(1)} \Rightarrow \oint \vec{B} \cdot d\vec{S} = 0 \quad \text{--- (2)}$$

Now By using Gauss divergence theorem

$$\oint \vec{B} \cdot d\vec{S} = \int (\nabla \cdot \vec{B}) dV$$

therefore (2) \Rightarrow

$$\boxed{\nabla \cdot \vec{B} = 0}$$

Maxwell Second eq^m.

Maxwell's Third Equation

$$\nabla \times \vec{E} = - \frac{d\vec{B}}{dt} \quad (\text{Faraday's law of electromagnetic induction})$$

Proof:

According to Faraday's first law of electromagnetic induction, induced emf is equal to rate of change of magnetic flux, i.e.

$$e = - \frac{d\phi}{dt}$$

e.m.f. is defined as $\int \vec{E} \cdot d\vec{l}$

$$\int \vec{E} \cdot d\vec{l} = - \frac{d\phi}{dt}$$

$$\int \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{s}$$

By Stokes' curl theorem,

$$\int (\nabla \times \vec{E}) \cdot d\vec{s} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{s}$$

$$\boxed{\nabla \times \vec{E} = - \frac{d\vec{B}}{dt}}$$

(By comparing both sides)

H.P.

Maxwell's IVth Equation:

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{d\vec{E}}{dt}$$

(Ampere's law with Maxwell modification)

Proof:

According to Ampere's circuital law

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I \quad \text{--- (1)}$$

(Line integral of magnetic field is μ_0 times the total current I).

By Stokes curl theorem

$$\oint \vec{B} \cdot d\vec{l} = \int (\vec{\nabla} \times \vec{B}) \cdot d\vec{s} \quad \text{--- (2)}$$

and

$$I = \int \vec{J} \cdot d\vec{s} \quad \text{--- (3)}$$

where \vec{J} \rightarrow current density

Now from (1) we have

$$\int (\vec{\nabla} \times \vec{B}) \cdot d\vec{s} = \mu_0 \int \vec{J} \cdot d\vec{s}$$

$$\therefore \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \quad \text{--- (4) (Integral form of Ampere's law)}$$

By taking divergence of both sides of eqⁿ
(4) we get

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 \vec{\nabla} \cdot \vec{J} \quad \text{--- (5)}$$

The left hand side of the equation, being a divergence of a curl vanishes, so we have

$$\vec{\nabla} \cdot \vec{J} = 0$$

However we know from the continuity equation

$$\vec{\nabla} \cdot \vec{J} + \frac{\partial \rho}{\partial t} = 0$$

Clearly in the presence of time dependent charge densities, the divergence of current density is non-vanishing, however Ampere's law demands that the divergence of \vec{J} must vanish. i.e. there is a contradiction. pointed out by Maxwell.

The problem was solved by Maxwell by introducing ~~the~~ term displacement 'current'.

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

(Maxwell Ist eqⁿ
or differential
form of Gauss law)

Continuity Equation.

$$0 = \vec{\nabla} \cdot \vec{J} + \frac{\partial \rho}{\partial t}$$

$$= \vec{\nabla} \cdot \left(\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

Notice that we have a quantity $\left(\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$ whose divergence is zero.

Therefore

$$\vec{J}_{\text{tot}} = \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Therefore Ampere's law

$$\vec{\nabla} \times \vec{B} = \mu_0 \left(\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

or

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$
$$\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

$\vec{D} \rightarrow$ Displacement vector.

$\frac{\partial \vec{D}}{\partial t} \rightarrow$ Term due to displacement current

\rightarrow Displacement current occurs due to time varying field.

Physical significance of Maxwell Equations:

(I) $\nabla \cdot \vec{E} = \rho / \epsilon_0$

or $\nabla \cdot \vec{D} = \rho$

- It is time independent equation.
- Since $\nabla \cdot \vec{E}$ is scalar, therefore charge density ρ is also scalar quantity.
- It is statement of Gauss law of electrostatics.

(II) $\nabla \cdot \vec{B} = 0$

- It is time independent equation.
- According to this equation isolated magnetic poles do not exist.
- Since $\oint \vec{B} \cdot d\vec{s} = 0$, i.e. number of lines of magnetic force leaving and entering a given volume are equal.
- It is statement of Gauss law in magnetism.

(III) $\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$

- It is time dependant equation

- It implies that time variation of magnetic field generates electric field.
- It is statement of Faraday's law of electromagnetic induction and negative sign justifies Lenz's law

$$(IV) \quad \nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\text{or } \nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

- It is time dependant equation
- It shows that magnetic field can be generated by current density vector and its time variation of \vec{D} .
- It relates magnetic field vector (\vec{B}) with electric displacement vector (\vec{D}) and current density vector (\vec{J}).
- It is statement of Ampere's law with Maxwell modification.